1/9 AXELROD et al. YOR920000210US2 (PJO)

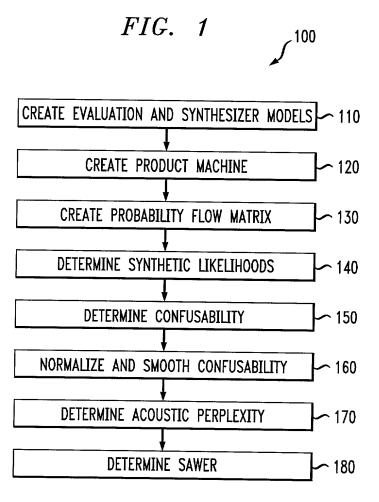


FIG. 2

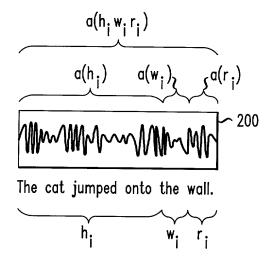
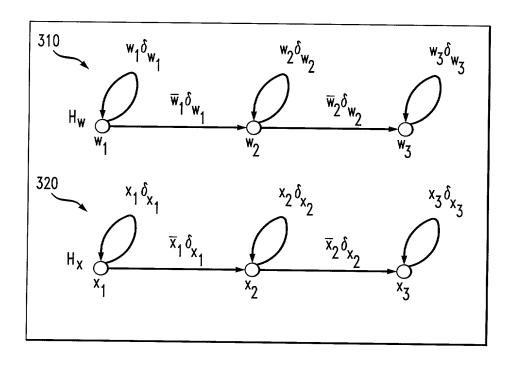


FIG. 3



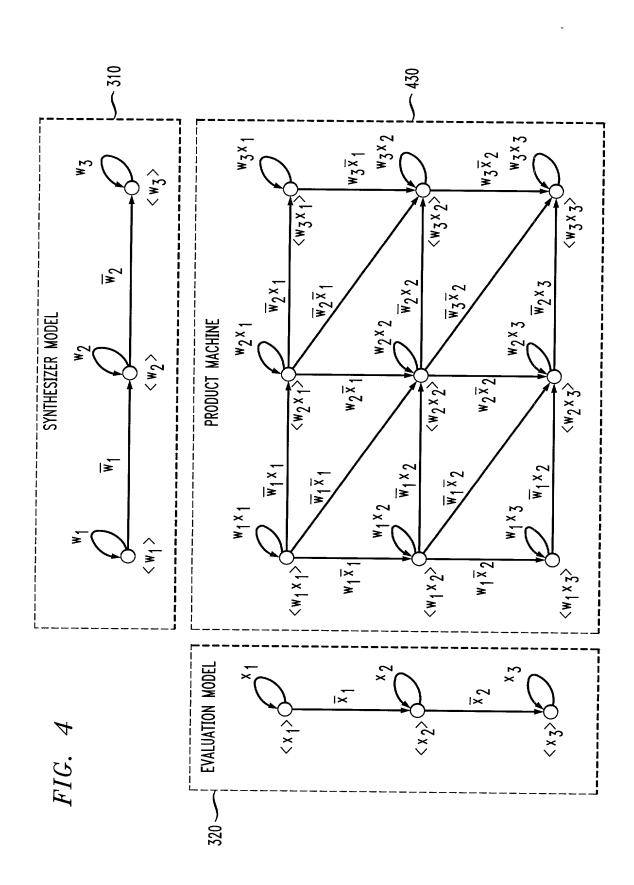


FIG. 5

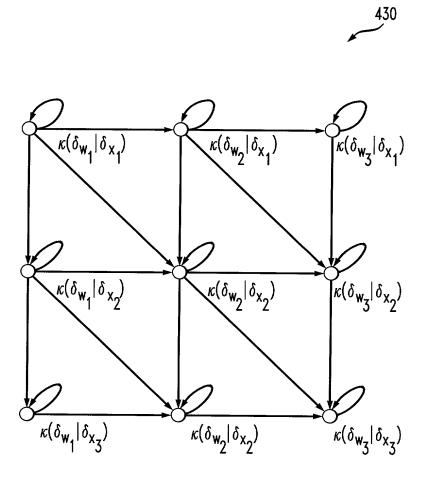
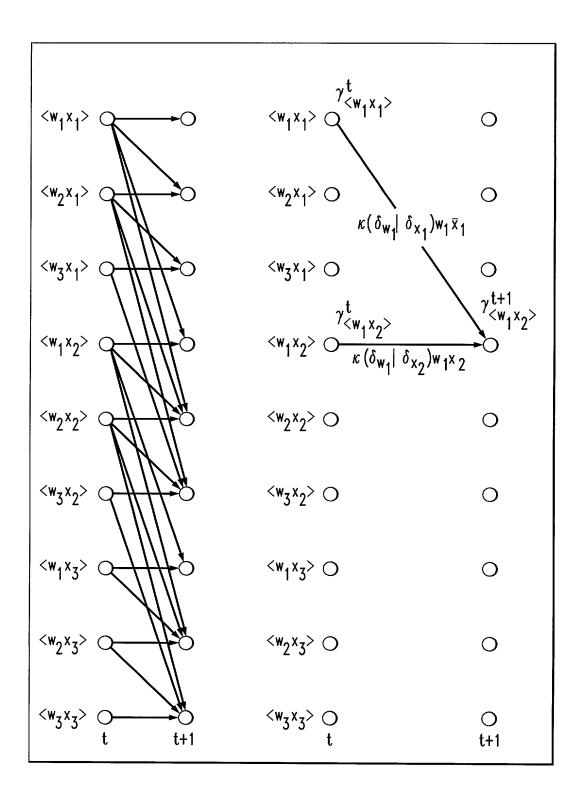


FIG. 6

630				∫ 600					
640	w ₁ × 1	w ₁ × 2	w ₁ x ₃	w ₂ × ₁	w ₂ x ₂	w ₂ x ₃	w ₃ × ₁	w ₃ × ₂	w ₃ x ₃
w ₁ × ₁	<u>601</u>	0	0	0	0	0	0	0	0
w ₁ x ₂	<u>602</u>	<u>603</u>	0	0	0	0	0	0	0
w ₁ x ₃	0	604	<u>605</u>	0	0	0	0	0	0
w ₂ x ₁	<u>606</u>	0	0	<u>607</u>	0	0	0	0	0
w2×2	608	<u>609</u>	0	<u>610</u>	<u>611</u>	0	0	0	0
w ₂ x ₃	0	612	613	0	614	<u>615</u>	0	0	0
₩3×1	0	0	0	<u>616</u>	0	0	<u>617</u>	0	0
w ₃ x ₂	0	0	0	618	619	0	620	621	0
w ₃ x ₃	0	0	0	0	<u>622</u>	<u>623</u>	0	<u>624</u>	<u>625</u>

FIG. 7



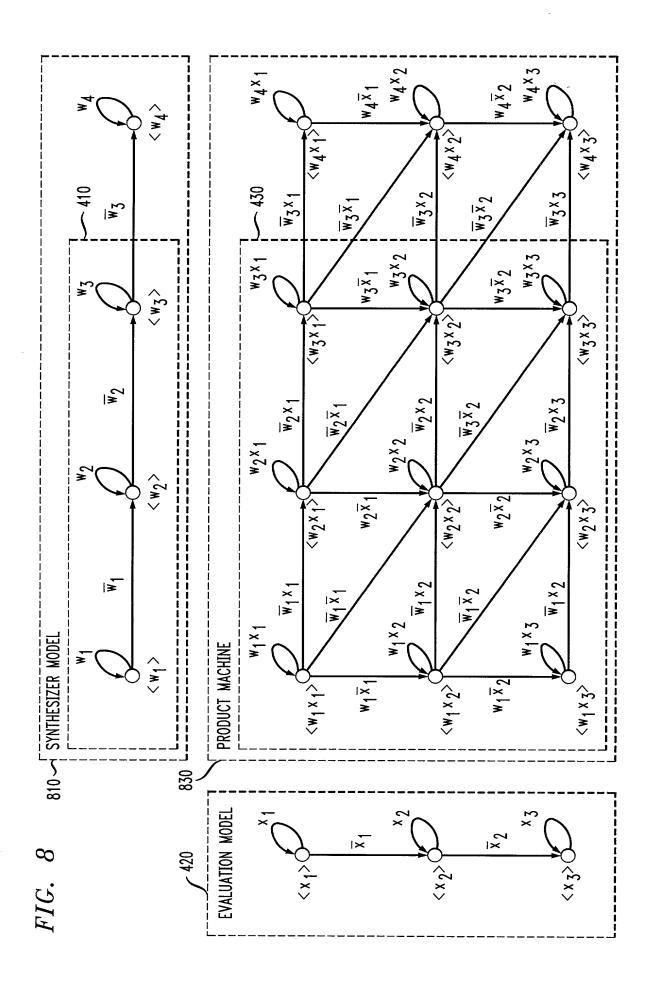


FIG. 9

